



Modelling non-isothermal absorption of vapour into expanding liquid sheets

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ABSTRACT

The problem of non-isothermal absorption of vapour into freely expanding liquid sheets is addressed in this study. This is done in the context of four models that characterise the coupled heat and mass transfer in the liquid phase: a nonlinear model retaining the effect of sheet growth, an approximate model for slowly increasing mass flow rate in the sheet, a large Lewis number model and finally, a boundary layer model. These models have been numerically or analytically solved and applied to the comparative analysis of two different working pairs, LiBr–H₂O and LiNO₃–NH₃, under conditions representative of adiabatic absorption in refrigeration systems. The limits of applicability of each model have been assessed and the sensitivity of the results to the sheet aperture angle, heat of absorption and initial subcooling has also been tested. For equal initial mass fraction and subcooling, the models indicate that Sherwood number and the rate of absorption in laminar expanding sheets for the LiNO₃–NH₃ solution are always superior to those for the LiBr–H₂O solution.

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1. Introduction

Absorption chillers and heat pumps have received growing attention over the last few decades. These machines allow the use of low-grade heat to produce a cooling effect, or a heat transformation to higher temperature levels, with no (or minimal) mechanical power consumption [1,2]. This makes them an attractive option in waste heat recovery, solar cooling and energy saving policies.

The absorber is one of the most performance limiting and volume demanding components of an absorption system. In the absorber the concentrated liquid solution absorbs the refrigerant vapour that comes from the evaporator. During this process, heat and mass transfer in the liquid solution are strongly coupled. Several configurations for the liquid and vapour streams in the absorber have been proposed: falling films, bubbles, sprays and droplets, liquid jets and sheets, etc. Absorption using drops, sprays, liquid jets and sheets takes place in an adiabatic chamber far from isothermal conditions. The cooling of the solution is carried out separately, in a specialised and efficient heat exchanger. This operation mode is generally referred to as adiabatic absorption [3].

The use of expanding liquid sheets in adiabatic absorbers may offer advantages in enhancing the mass transfer as well as in reducing both volume and cost of the system. In this work, following the terminology of Simpson and Lynn [4], an expanding liquid sheet refers to any free stream of solution that expands in multiple directions from one common origin, while its thickness progres-

sively reduces. Flat-fan sheets, conical sheets and radially expanding sheets are significant examples of this flow configuration. A smaller injection pressure is required to produce an expanding sheet than is required to atomize the liquid in a spray. There is a broad literature concerning the dynamics of expanding liquid sheets. Classical studies of these spreading sheets can be found in [5–9].

Several works have been conducted in order to understand the heat and mass transfer in expanding liquid sheets; however, most of these studies are not directly devoted to absorption chillers and heat pumps.

One of the earliest experimental works attending the problem of water vapour condensation on subcooled conical swirling sheets was that performed by Weinberg in 1952 [10]. In this work, large temperature variations, and therefore high rates of condensation, were observed in the sheet region of the spray. Other subsequent investigations on condensation also addressed the direct measurement of temperatures in conical sheets of water [11,12] and R113 refrigerant [13]. Condensation on laminar flat-fan sheets was studied by Hasson et al. [14] and Tamir and Hasson [15]. This second work also examines the evaporation process in flat-fan sheets.

The seminal work of Hasson et al. in 1964 [16] includes the first analytical approximation to the problem of heat transfer in a smooth fan-shaped sheet of water during vapour condensation. The energy equation for flat-fan sheets was resolved in the form of a series solution, neglecting the effect of mass growth due to condensation at the sheet surface. Comparison of these results to previous measurements [14,15] demonstrates a qualitative similarity. Lee and Takin [11] developed a numerical simulation of the condensation in the laminar sheet region of a conical spray

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Nomenclature

a_0	width of the sheet at the nozzle exit, $2r_0 \sin(\theta/2)$, m	y	streamwise distance relative to the initial sheet section, m
C_p	specific heat of the solution, $\text{J kg}^{-1} \text{K}^{-1}$	z	transversal coordinate, m
$c_1 c_2$	equilibrium constants of the solution	<i>Greek symbols</i>	
D	diffusion coefficient of absorbate in the solution, $\text{m}^2 \text{s}^{-1}$	α	thermal diffusivity of the solution, $\text{m}^2 \text{s}^{-1}$
d_{eq}	nozzle equivalent diameter, $2(a_0 \varepsilon_0 / \pi)^{1/2}$, m	δ_1, δ_2	heat of absorption normalisations
F	approach to equilibrium factor, X_b	δ_3	normalised subcooling
h	specific enthalpy of the solution, J kg^{-1}	ΔT_{sub}	initial subcooling of the solution, $^\circ\text{C}$
h_m	local mass transfer coefficient, m s^{-1}	ΔX_{lm}	logarithmic mean absorbent mass fraction difference
\bar{h}_m	mean mass transfer coefficient, m s^{-1}	$\Delta \bar{X}_{lm}$	normalised logarithmic mean mass fraction difference, $\Delta X_{lm} / X_0 \delta_3$
h_v	specific enthalpy of the vapour, J kg^{-1}	ε	sheet thickness, m
k	thermal conductivity of the solution, $\text{W m}^{-1} \text{K}^{-1}$	ε_0	sheet thickness at the initial position of the sheet, m
L_{abs}	specific heat of absorption, J kg^{-1}	$\hat{\varepsilon}$	normalised sheet thickness, $\varepsilon / \varepsilon_{NA}$
L_{abs}^*	equivalent specific heat of absorption, L_{abs} / X_0 , J kg^{-1}	η	normalised transversal coordinate, $2z / \varepsilon$
Le	solution Lewis number, α / D	θ	aperture angle of the sheet, degree
\dot{m}	solution mass flow rate of the sheet, $\pi \varepsilon r_0 \rho V_0 / 180$, kg s^{-1}	ξ	dimensionless radial coordinate, r / r_0
\dot{m}_v	mass flow rate of absorbed vapour in the sheet, $\dot{m} - \dot{m}_0$, kg s^{-1}	ξ_{tr}	normalised radial coordinate, $(\xi^3 - 1) / 3Pe_t Le$
\dot{m}_v''	absorbate mass flux at the interface, $\text{kg m}^{-2} \text{s}^{-1}$	ρ	solution density, kg m^{-3}
\dot{m}_0	initial mass flow rate of the solution, kg s^{-1}	ϕ	self-similar variable, $(1 - \eta) / 2\xi^{1/2}$
p_v	absorbate vapour pressure, Pa	ψ	dimensionless streamwise distance, $2y / \varepsilon_0$
Pe_t	transversal velocity Peclet number, $V_0 \varepsilon_0^2 / 4\alpha r_0$	ω	cone angle in conical sheets, degree
r	radial coordinate, m	<i>Subscripts</i>	
r_0	radial coordinate at the initial sheet section, m	b	bulk conditions
Sh	local Sherwood number, $h_m \varepsilon / 2D$	BL	boundary layer approximation
\bar{Sh}	mean Sherwood number, $\bar{h}_m \bar{\varepsilon} / 2D$	\max	maximum value
T	temperature of the solution, $^\circ\text{C}$	NA	non-absorption conditions
\hat{T}	normalised solution temperature, $(T - T_0) / (T_\infty - T_0)$	NE	non-expanding free sheets
V_r	radial velocity of the solution, m s^{-1}	s	conditions at the sheet surface
V_z	transversal velocity of the solution, m s^{-1}	st	boundary layer stable conditions
V_0	initial radial velocity, m s^{-1}	v	vapour
X	absorbent mass fraction [mass of absorbent/mass of solution]	0	initial conditions
$X_{eq}(T)$	equilibrium absorbent mass fraction $c_1 T + c_2$	∞	complete adiabatic saturation, fully developed conditions
\bar{X}	normalised mass fraction, $(X - X_0) / (X_\infty - X_0)$		

whose aperture angle and velocity had been previously obtained in [17]. More recently, Takahashi and co-workers [12] extended the series solution of Hasson et al. [16] to the case of condensation in a swirling conical sheet. In all of these works, the predicted mean temperature in the sheet underestimated the experimental data. Turbulence transport in the sheet was suggested as a factor that could produce such discrepancies [12].

In 1972 Tamir and Rachmilev [18] published their experimental results on absorption of CO_2 in a “rapid laminar fan-shaped water sheet”. The temperature in the sheet remained constant because of the low heat of absorption of CO_2 into water. Using the analogy between heat and mass transfer, Tamir and Rachmilev [18] adapted the series solution for the flat-fan sheets of Hasson et al. [16] to the problem of isothermal absorption. Their analytical model was found to be in good agreement with measurements. Simpson and Lynn [4] experimentally characterised the desorption of various substances such as oxygen, Freon 114 and *n*-butane, from laminar flat-fan and conical sheets of water/salt solutions. A similar conversion of the Hasson et al. [16] series solution was also performed by Simpson and Lynn [4] in their model estimation of isothermal desorption, and reasonable concordance between the model and the experimental data was found. For turbulent expanding sheets however, the concordance was only qualitative, necessitating a corrected empirical model [19]. In all of these works on absorption and desorption, conditions near equilibrium were detected even at extremely short sheet lengths.

In a work dealing with the problem of water vapour absorption into sprays of aqueous lithium bromide solution, Ryan et al. [20]

indicated that the short sheet region of a spray before breaking into droplets had a relevant contribution in their measurements of the global absorption in conical and flat-fan sprays. Neglecting the sheet thickness variation they used a sheet of constant thickness (from [16]) in order to incorporate the contribution of the short sheet region into the spray absorption modelling.

The aim of the present work is to extend the aforementioned numerical and analytical models for expanding sheets to the case of non-isothermal vapour absorption. Conditions representative of adiabatic absorbers in refrigeration systems are selected to the integration of the equations. The coupled heat and mass transfer models presented in this investigation are also inspired by the simulation techniques developed for absorption in falling films. Excellent reviews, containing numerical, analytical and experimental data for absorption in falling films can be found in the works of Grossmann [21] and Killion and Garimella [22].

2. Expanding sheet adiabatic absorption

Fig. 1 presents a conceptual drawing of an expanding sheet adiabatic absorber. It consists of an adiabatic chamber into which the concentrated solution of an absorption system is injected, producing an expanding liquid stream such as a flat-fan, conical, or radially expanding sheet (see Fig. 1a, b and c, respectively). In Fig. 1c, a 360° nozzle generates the disk sheet, but other methods can also be used (for example the impingement of two round liquid jets). The liquid solution is composed of two substances: absorbent and absorbate (also known as refrigerant). Additionally, there is a

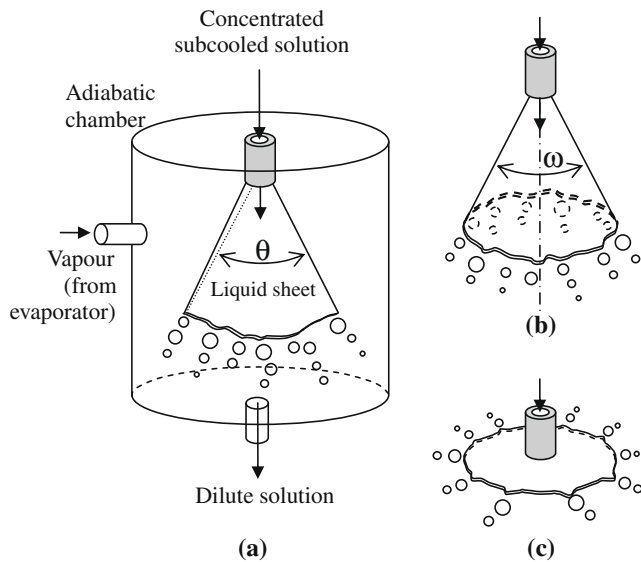


Fig. 1. Schematic diagram of an adiabatic absorber containing a flat-fan sheet of liquid solution (a). Other liquid flow configurations are: conical sheet (b), and disk sheet (c).

flow of absorbate that is in the vapour phase, close to saturation conditions, that enters the chamber. Absorbate vapour comes from the evaporator of the absorption machine where it acts as a refrigerant working fluid.

The liquid solution enters the chamber in a subcooled state; that is, its temperature is initially less than the equilibrium temperature at the pressure p_v of absorbate vapour in the chamber. As a result, the absorbate vapour is spontaneously absorbed by the liquid sheet, decreasing the solution absorbent mass fraction from the input (concentrated solution) to the output (diluted solution) of the absorber.

In this work, results will be compared between two different working pairs of binary solution: aqueous lithium bromide solution, LiBr–H₂O; and lithium-nitrate–ammonia solution, LiNO₃–NH₃. Here H₂O and NH₃ are the absorbate (or refrigerant) substances and the remaining substances the absorbent. Table 1 contains basic properties of these working pairs. Properties for the pair LiNO₃–NH₃ correspond to the operating conditions of a low-pressure double-stage absorption chiller fed with a low-grade heat source [23]. Working conditions for the pair LiBr–H₂O [24–26], have been chosen so that the solution operates with the same inlet temperature T_0 and mass fraction X_0 as the ammonia solution pair. Mass diffusivity D of water into LiBr–H₂O solution is taken from [27].

Table 1
Working pairs properties corresponding to similar initial conditions ($T_0 = 40$ °C and $X_0 = 0.633$).

	LiBr–H ₂ O	LiNO ₃ –NH ₃
p_v [Pa]	9.3×10^2	2.36×10^5
ρ [kg m ⁻³]	1789	1132
C_p [J kg ⁻¹ K ⁻¹]	1830	2620
α [m ² s ⁻¹]	1.37×10^{-7}	5.07×10^{-7}
D [m ² s ⁻¹]	1.54×10^{-9}	0.74×10^{-9}
c_1 [°C ⁻¹]	4.85×10^{-3}	3.72×10^{-3}
c_2 [-]	0.385	0.434
L_{abs} [J kg ⁻¹]	2.44×10^6	1.31×10^6

3. Physical model and general assumptions

The physical model to be considered in the simulation is schematically represented in Fig. 2. A free expanding sheet of liquid solution flows from an injector, a nozzle or a small impinging plate. Both sides of the liquid sheets are in contact with a stagnant absorbate (refrigerant) in the vapour phase. This is the only gaseous substance in the chamber. The liquid sheet spreads outwardly in divergence directions from a virtual origin. Expansion of the flow causes the thickness ε of the liquid sheet to gradually narrow in the stream direction. The sheet exits the nozzle or injector at $r = r_0$, from this precise moment it starts to absorb the surrounding vapour.

When the divergence directions of the flow are in a plane, as they are in Fig. 2, the liquid sheet adopts the shape of a flat-fan or a radially expanding disk (the latter if the angle θ covered by the sheet reaches 360°). Conical sheets are created if the directions of divergence form a hollow cone. This can be approximated by a flat-fan sheet rolled up along the axis of a cone whose angle ω (see Fig. 1b) satisfies $\omega = 2 \arcsin(\theta/\theta_{\max})$, being $\theta_{\max} = 360^\circ$.

The mass absorption into the expanding sheet of Fig. 2, through two sides of the sheet, is strongly coupled with the transfer of heat of absorption that is released at the surface. In formulating the absorption model the following assumptions are made:

- Steady state conditions are assumed.
- The liquid sheet flow is laminar and its velocity is high enough to neglect the effects of the gravitational acceleration as well as interfacial liquid–vapour drag on the sheet hydrodynamics.
- The contribution of the borders of the sheet (rims) to the total amount of absorbed refrigerant is neglected.
- Finite dilution at the interface, transversal velocity V_z , and growth of mass rate in the sheet due to absorption are considered.
- At the free surface of the sheet, instantaneous equilibrium arises between the solution temperature and the species mass fraction.
- At the initial position of the sheet, $r = r_0$, the temperature and mass fraction profiles of the solution are uniform and equal to T_0 and X_0 , respectively. This holds except at the sheet surface where the mass fraction decreases to $X_{eq}(T_0)$ on account of the equilibrium condition.
- The mixture properties (ρ , C_p , α , D) and heat of absorption are considered to be constant under the narrow range of temperatures and species mass fractions reached by the present model.
- Heat transfer from the solution to the vapour (or to its surroundings) and viscous thermal dissipation are neglected.

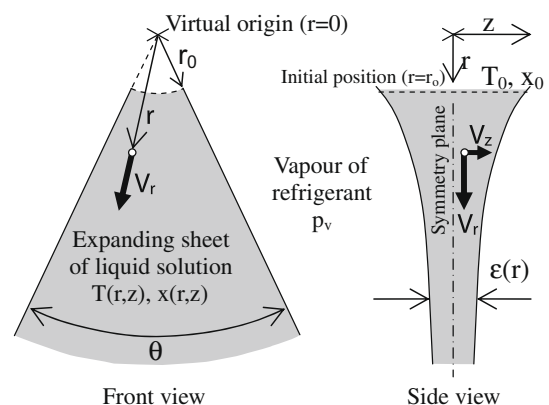


Fig. 2. Physical model and coordinate system.

Many of these simplifying assumptions are representative of practical operating conditions in adiabatic absorption and are also common to many models in falling-film absorption. At this regard, it is important to note that in non-adiabatic absorption large increments of absorbate mass fraction and temperature can occur, being in that case recommendable to calculate the local variation of working pair properties with X and T (see for example [28]). This contrasts with adiabatic absorption for which the assumption of unvarying properties in the mixture is particularly suited because potential increments of T and, above all, X are significantly smaller [3,23], as demonstrated in Appendix A.

4. Flow field in the sheet

Because it is assumed constant density in the flow, the liquid sheet hydrodynamics do not depend on temperature and species mass fraction. Therefore, the velocity field in an expanding sheet can be deduced at the onset for later use in the heat and mass transfer equations. Owing to stream-wise momentum conservation and assuming invariance in angular direction, the radial velocity V_r of the mixture in a smooth laminar expanding sheet can be considered constant [4,6,15–18,29]:

$$V_r = V_0 \tag{1}$$

where V_0 is the radial initial velocity of the liquid sheet at $r = r_0$. Thus, from the continuity equation in polar coordinates and considering null angular velocity, it is straightforward to obtain the transversal velocity V_z of the mixture in the sheet:

$$V_z = -\frac{V_0 z}{r} \tag{2}$$

where z is the transversal coordinate (Fig. 2). Observe that V_z is null at the sheet symmetry plane $z = 0$ and negative for $z > 0$. This means that, given any point in the sheet, an incoming flow of solution in the transversal direction arises in order to replace the solution that is expanding radially in the sheet.

It should be noted that sheet retraction at the rims [30] and disintegration [5] has not been considered. As a result, the model should only be applied to smooth flow conditions in the region before sheet instabilisation and break-up.

5. Energy and mass fraction equations

5.1. Complete nonlinear model

Transport of heat and mass within the liquid sheet is governed by advective and diffusive processes. No generation of species takes place in the problem and diffusion of heat and mass in the sheet in the streamwise direction can be disregarded as compared to diffusion in the transverse direction. Under these simplifications and the assumptions presented previously, the differential equations for the conservation of absorbent mass and solution energy [31] in any point of an expanding sheet are (respectively) expressed in polar coordinates (Fig. 2) as follows:

$$\frac{1}{r} \frac{\partial}{\partial r} (rV_r X) + \frac{\partial}{\partial z} (V_z X) = D \frac{\partial^2 X}{\partial z^2} \tag{3}$$

$$\frac{1}{r} \frac{\partial}{\partial r} (rV_r T) + \frac{\partial}{\partial z} (V_z T) = \alpha \frac{\partial^2 T}{\partial z^2} \tag{4}$$

where X and T are the local mass fraction of absorbent and the solution temperature in the liquid sheet.

Because of the symmetry of the problem, Eqs. (3) and (4) are solved in a domain comprising only half the volume of the liquid

sheet. The boundary conditions referring to this domain are presented in the following lines.

- (i) The absorbent mass fraction and solution temperature at the initial section of the expanding sheet are:

$$X(r_0, z) = \begin{cases} X_0, & 0 \leq z < \frac{\varepsilon_0}{2} \\ X_{st}, & z = \frac{\varepsilon_0}{2} \end{cases} \tag{5}$$

$$T(r_0, z) = \begin{cases} T_0, & 0 \leq z < \frac{\varepsilon_0}{2} \\ T_{st}, & z = \frac{\varepsilon_0}{2} \end{cases} \tag{6}$$

Here $\varepsilon_0 = \varepsilon(r_0)$ is the thickness of the sheet at the initial position. As in the work of Brauner [32], initial values of X and T at the surface have been selected equal to the values provided by the boundary layer theory (Section 5.4) near the initial position:

$$X_{st} = X_0 \frac{L_{abs} c_1 + X_{eq}(T_0) c_D Le^{1/2}}{L_{abs} c_1 + x_0 c_D Le^{1/2}} \tag{7.a}$$

$$T_{st} = \frac{X_{st} - c_2}{c_1} \tag{7.b}$$

Note that, due to the parabolic character of Eqs. (3) and (4), results for X and T are weakly affected by their initial values at the sheet surface. In fact, as will be confirmed later on, large Lewis number, $Le \gg 1$, causes rapid thermal dissipation as compared to mass transport. This avoids a substantial increase of temperature at the surface of the sheet $z = \varepsilon_0/2$ in $r = r_0$ and the temperature profile in Eq. (6) may be considered constant.

- (ii) Gradients along the transversal direction are null at the plane of symmetry:

$$\left. \frac{\partial X}{\partial z} \right|_{z=0} = 0, \quad r \geq r_0 \tag{8}$$

$$\left. \frac{\partial T}{\partial z} \right|_{z=0} = 0, \quad r \geq r_0 \tag{9}$$

- (iii) The equilibrium mass fraction of absorbent at the free surface, under small thermal variations, is commonly expressed (see for example, [23,33]) as a linear function of the solution temperature:

$$X(r, z_s) = X_{eq}(T_s) = c_1 \cdot T(r, z_s) + c_2 \tag{10}$$

where $z_s = \varepsilon/2$ and T_s are the values of the z coordinate and temperature at the free surface, respectively. The constants c_1 and c_2 are properties of the mixture (Table 1) and depend on the absorbate vapour pressure p_v which is assumed constant throughout the chamber.

- (iv) The absorbed mass and the heat of absorption released at the sheet surface are both transported by advection and diffusion into the fan sheet. An energy balance at the free surface of the fan sheet provides the next boundary condition [34]:

$$k \left. \frac{\partial T}{\partial z} \right|_s = L_{abs} \dot{m}_v'' \tag{11}$$

where L_{abs} is the specific heat of absorption of vapour in the solution and \dot{m}_v'' is the mass flux of absorbate vapour that is absorbed at the free surface of the expanding liquid sheet:

$$\dot{m}_v'' = -\frac{\rho D}{X_s} \left. \frac{\partial X}{\partial z} \right|_s \tag{12}$$

Advection at the sheet surface is due to the motion of the liquid solution relative to the free surface. Under the com-

mon operating conditions of absorption systems, *Finite dilution* at the interface (i.e. X_s not close to unity) will make advective terms relevant [22]. Nakoryakov and co-workers [35] also included advection in their model of absorption into a stagnant layer. Eq. (11) is equivalent to the expression deduced by inclusion of the net flow motion term (due in this case to absorbate diffusion) into Fick's law in a fixed coordinate reference system [36,32].

One should observe that, as radial diffusion terms are negligible, the conservation equations ((3) and (4)) are parabolic and no boundary conditions are required downstream of the domain.

The following differential equation can be derived for the sheet thickness ε from a mass balance in the fan sheet:

$$\frac{1}{r} \frac{d}{dr} (r \varepsilon \rho V_0) = - \frac{2D\rho}{X_s} \frac{\partial X}{\partial z} \Big|_s \quad (13)$$

where ε_0 is the initial condition of ε in this equation. This last expression is coupled with the heat and mass balance equations for the sheet.

For convenience, the following transformations will be used for the radial and transversal coordinates, respectively:

$$\hat{\xi} = \frac{1}{3Pe_t Le} (\xi^3 - 1) \quad (14)$$

$$\eta = \frac{z}{z_s} = \frac{2z}{\varepsilon} \quad (15)$$

where $\xi = r/r_0$ and Pe_t is the Peclet number for the initial transversal velocity of the solution at the interface:

$$Pe_t = \frac{|V_{z,s}| \cdot z_s}{\alpha} \Big|_{r=r_0} = \frac{V_0 \varepsilon_0^2}{4r_0 \alpha} \quad (16)$$

The normalised variable $\hat{\xi}$ resembles the dimensionless radial distance used by Tamir and Rachmiev [18]. The transversal coordinate has been normalised via Eq. (15) in order to obtain $\eta = 1$ at the free surface. This change of variables not only simplifies the conservation equations, but also converts the physical domain of the expanding sheet into a rectangular domain ($\hat{\xi} \geq 0, 0 \leq \eta \leq 1$).

Under the proposed transformation of coordinates, the differential equations (3), (4) and (13) for the coupled heat and mass transfer during non-isothermal absorption of vapour into an expanding sheet become:

$$\frac{\partial \hat{X}}{\partial \hat{\xi}} = \frac{\eta}{\hat{\varepsilon}} \frac{d\hat{\varepsilon}}{d\hat{\xi}} \frac{\partial \hat{X}}{\partial \eta} + \frac{1}{\hat{\varepsilon}^2} \frac{\partial^2 \hat{X}}{\partial \eta^2} \quad (17.a)$$

$$\frac{\partial \hat{T}}{\partial \hat{\xi}} = \frac{\eta}{\hat{\varepsilon}} \frac{d\hat{\varepsilon}}{d\hat{\xi}} \frac{\partial \hat{T}}{\partial \eta} + \frac{Le}{\hat{\varepsilon}^2} \frac{\partial^2 \hat{T}}{\partial \eta^2} \quad (17.b)$$

$$\frac{d\hat{\varepsilon}}{d\hat{\xi}} = \frac{1}{\delta_3^{-1} - \hat{X}(\hat{\xi}, \eta = 1)} \frac{1}{\hat{\varepsilon}} \frac{\partial \hat{X}}{\partial \eta} \Big|_{\eta=1} \quad (17.c)$$

where $\hat{X} = (X - X_0)/(X_\infty - X_0)$ and $\hat{T} = (T - T_0)/(T_\infty - T_0)$ are the normalised temperature and mass fraction, and where X_∞ and T_∞ are the values reached under complete adiabatic saturation (see Appendix). $\hat{\varepsilon} = \varepsilon/\varepsilon_{NA}$ is the normalised sheet thickness, ε_{NA} being the thickness of an expanding sheet that does not absorb vapour as it is not initially subcooled. Applying mass conservation, it is straightforward to demonstrate that $\varepsilon_{NA} = \varepsilon_0 r_0 / r$.

From the previous transformations, the boundary conditions of Eqs. (17) become:

$$\hat{X}(\hat{\xi} = 0, \eta) = \begin{cases} 0, & 0 \leq \eta < 1; \\ \hat{X}_{st}, & \eta = 1 \end{cases} \quad \frac{\partial \hat{X}}{\partial \eta} \Big|_{\eta=0} = 0, \quad \hat{\xi} \leq 0 \quad (18.a)$$

$$\hat{T}(\hat{\xi} = 0, \eta) = \begin{cases} 0, & 0 \leq \eta < 1; \\ \hat{T}_{st}, & \eta = 1 \end{cases} \quad \frac{\partial \hat{T}}{\partial \eta} \Big|_{\eta=0} = 0, \quad \hat{\xi} \leq 0 \quad (18.b)$$

$$\hat{X}(\hat{\xi}, \eta = 1) + \delta_2 \hat{T}(\hat{\xi}, \eta = 1) = 1 + \delta_2, \quad \hat{\xi} \geq 0 \quad (18.c)$$

$$Le \frac{\partial \hat{T}}{\partial \eta} \Big|_{\eta=1} = \frac{\delta_1}{\delta_2 X_0 \cdot (1 - \delta_3 \cdot \hat{X}(\hat{\xi}, \eta = 1))} \frac{\partial \hat{X}}{\partial \eta} \Big|_{\eta=1} \quad (18.d)$$

$$\hat{\varepsilon}(\hat{\xi} = 0) = 1 \quad (18.e)$$

where δ_1, δ_2 and δ_3 are defined as:

$$\delta_1 = \frac{c_1 L_{abs}}{C_p} \quad (19)$$

$$\delta_2 = \frac{X_\infty - X_{eq}(T_0)}{X_0 - X_\infty} \quad (20)$$

$$\delta_3 = 1 - \frac{X_\infty}{X_0} = \frac{c_1 \cdot \Delta T_{sub}}{X_0 \cdot (1 + \delta_2)} \quad (21)$$

with $\Delta T_{sub} = T_{eq}(X_0) - T_0$ the initial subcooling of a sheet flow with $T_{eq}(X_0) = (X_0 - c_2)/c_1$. Substituting X_∞ from (A.3) into the Eqs. (20) and (21), it is easy to find that:

$$\delta_2 = \frac{\delta_1}{X_0} \quad (22)$$

Taking into account Eq. (22), the normalised expanding sheet Eqs. (17) and (18) only contain three dimensionless groups: the Lewis number Le , the dimensionless heat of absorption δ_2 and the normalised subcooling δ_3 . Notice that these sheet equations form a nonlinear system for which no evident analytical solution exists. The sources of this nonlinearity are present in Eqs. (17) and (18.d): the term reflecting the mass flow rate increase and the term describing the surface advective velocity.

5.2. Slowly increasing mass flow rate ($\dot{m} \approx \text{const.}$) model

Subcooling in refrigeration is commonly conducive to $\delta_3 \ll 1$. This immediately gives, $d\hat{\varepsilon}/d\hat{\xi} \ll 1$, which means that the sheet mass flow rate $\dot{m} = \pi \varepsilon r \theta \rho V_0 / 180$ increases slowly along radial direction. For sufficiently small values of δ_3 , it is possible to simplify the nonlinear equations (17) in order to obtain the following linear system for the coupled heat and mass transfer in an expanding sheet:

$$\frac{\partial \hat{X}}{\partial \hat{\xi}} = \frac{\partial^2 \hat{X}}{\partial \eta^2} \quad (23.a)$$

$$\frac{\partial \hat{T}}{\partial \hat{\xi}} = Le \frac{\partial^2 \hat{X}}{\partial \eta^2} \quad (23.b)$$

Boundary conditions for this slowly increasing mass flow rate model are still defined by Eqs. (18), except for Eq. (18.d) which collapses to:

$$Le \frac{\partial \hat{T}}{\partial \eta} \Big|_{\eta=1} = \frac{\partial \hat{X}}{\partial \eta} \Big|_{\eta=1} \quad (24)$$

It can be shown that the above linearised system of equations is equivalent to the expressions obtained using a simplified model that considers infinite dilution at the interface (e.g. null advective transport at the surface) in which L_{abs} is substituted by a modified specific heat of absorption $L_{abs}^* = L_{abs}/X_0$. Observe that the linearity of the Eqs. (23) and (24) simplifies their integration.

5.3. Large Lewis ($Le \gg 1$) model

The Lewis number, Le , is much greater than one in most of the mixtures used in absorption systems. This means that diffusion heat transfer is more effective than mass transfer along the transversal direction. As a result \hat{T} will only show a relevant dependence on $\hat{\xi}$. Under this simplification, Eq. (23.b) is no longer useful and the following energy balance is adopted in the whole section of the sheet:

$$\frac{d(\dot{m}h)}{dr} = 2 \frac{\pi}{180} \theta \dot{m}''_v h_v \quad (25)$$

Here, $h = C_p(T - T_{ref})$ is the specific enthalpy of the liquid solution, taking T_{ref} as a reference temperature.

Subsequently, under the approximation of large Lewis number and considering $\dot{m} \approx const.$, the system of equations to be solved is composed of the rearranged Eqs. (25) and (18.c),

$$\left. \frac{\partial \hat{X}}{\partial \eta} \right|_{\eta=1} = - \frac{1}{\delta_2} \left. \frac{\partial \hat{X}}{\partial \hat{\xi}} \right|_{\hat{\xi}=1} \quad (26.a)$$

$$\hat{T}(\hat{\xi}) = - \frac{1}{\delta_2} \hat{X}(\hat{\xi}, \eta = 1) + \frac{1}{\delta_2} + 1 \quad (26.b)$$

along with Eq. (23.a) and the initial and symmetry boundary conditions for \hat{X} , Eq. (18.a). Note that, when $Le \gg 1$, the initial conditions at the free surface collapses to $\hat{X}(0, \eta = 1) = 1 + \delta_2$ and $\hat{T}(0, \eta = 1) = 0$. The main advantage of this system of equations for $Le \gg 1$ is that their analytical solution is greatly simplified. This is especially true as the normalised mass fraction \hat{X} can be solved first and then introduced in Eq. (26.b) to calculate the normalised temperature \hat{T} .

5.4. Boundary layer model

A boundary layer model can be chosen to describe the initial region in which changes of temperature and species mass fraction in the expanding sheet only occur in a thin layer, close to the free surface. The coupled heat and mass transport in the boundary layers can be modelled as if they were in a semi-infinite volume of liquid, for instance comprising $-\infty < \eta < 1$ and $\hat{\xi} \geq 0$, as the boundary layers from opposite sheet surfaces do not touch each other. As will be shown in the simulation results, in this region \hat{X} and \hat{T} at the free surface stabilise to equilibrium values, \hat{X}_{st} and \hat{T}_{st} , in the same manner as is found in falling-film absorption [21]. A closed-form solution to the system of Eqs. (23) in such a semi-infinite domain can be obtained by means of the following self-similar variable [31]:

$$\phi = \frac{1 - \eta}{2^{\hat{\xi}^{1/2}}} \quad (27)$$

The transformed equations using (27) solely depend on ϕ and their integration reduces to expressions that depend linearly on the error function, $erf(x) = 2\pi^{-1/2} \int_0^x e^{-u^2} du$:

$$\hat{X}(\phi) = \hat{X}_{st} \cdot [1 - erf(\phi)] \quad (28.a)$$

$$\hat{T}(\phi) = \hat{T}_{st} \cdot [1 - erf(\phi/Le^{1/2})] \quad (28.b)$$

where the stable values of mass fraction and temperature at the free surfaces are:

$$\hat{X}_{st} = \frac{Le^{1/2} \cdot (\delta_2 + 1)}{\delta_2 + Le^{1/2}} \quad (29.a)$$

$$\hat{T}_{st} = \frac{\delta_2 + 1}{\delta_2 + Le^{1/2}} \quad (29.b)$$

Eqs. (28) and (29) are almost identical to the expressions first obtained by Nakoryakov and Grigorieva [37] regarding absorption into a falling film over an isothermal wall. Though similar, the expressions for \hat{T}_{st} or \hat{X}_{st} in the present investigation and in [37] differ, as no advective velocity relative to the interface was included in [37].

The point $\hat{\xi}_{tr}$, where a transition starts between boundary layer and fully developed flow in the sheet, can be roughly estimated as the radial position wherein temperature at the symmetry plane of the sheet increases to a sensible fraction c_k of \hat{T}_{st} after the merger of opposing thermal boundary layers:

$$\hat{\xi}_{tr} = \frac{1}{4 \cdot Le \cdot [inverf(1 - c_k)]^2} \quad (30)$$

with *inverf*, the inverse function of the error function, and $0 < c_k < 1$.

6. Solving procedure

6.1. Numerical solution of the nonlinear model

A finite-difference numerical method [38] has been developed for the solution of the set of parabolic differential equations (17) together with their boundary conditions (18). It consists of a semi-implicit numerical scheme that marches the solution along the radial direction of the sheet from the initial position $r = r_0$. A detailed description of this method can be found in [34]. Since the equations involved in the problem are nonlinear, their numerical solution is computationally demanding inasmuch as it requires the inversion of a large matrix during every integration step. The numerical scheme has been programmed in a personal computer and the accuracy of the results has been assessed through the sensitivity of the calculated \hat{X} and \hat{T} on the mesh size, as well as the concordance between global energy and mass balances in the sheet.

Table 2 contains geometric and hydrodynamic parameters that were selected for the simulated reference cases. Their values have been obtained from a standard flat-fan spray nozzle whose exit section has $d_{eq} = 2$ mm equivalent diameter and $a_0 = 9.3$ mm width, operating at an injection pressure between 1.0 and 2.0 bar.

6.2. Analytical and numerical solution of the $\dot{m} \approx const.$ model

The assumption of slowly increasing mass rate (described earlier) leads to a simplified set of linear differential equations (Eqs. (23), (18.a–c) and (24)). Thus, it is possible to follow a procedure analogous to the one first presented by Nakoryakov and Grigorieva [39] on falling films in order to obtain a series solution of \hat{X} and \hat{T} . An interesting result of the series solution of \hat{X} and \hat{T} is that it depends on the integral values of mass fraction and temperature at the initial position ($\hat{\xi} = 0$) but not on the specific values of \hat{X} and \hat{T} at the free surface ($\hat{\xi} = 0, \eta = 1$). In practice, obtaining the eigenvalues of the series becomes cumbersome while the resulting solution converges quite slowly. It is also found that the series solution values for \hat{X} and \hat{T} ripple near the initial position of the expanding sheet on account of numerical artifacts produced by the sharp boundary condition at $\hat{\xi} = 0$. Similar effects have been also reported in [33,40]. Therefore, all the results presented in this study under the $\dot{m} \approx const.$ approximation have been integrated numer-

Table 2
Reference values of sheet geometry and operation.

ϵ_0 [m]	r_0 [m]	θ [°]	V_0 [m s ⁻¹]
3.38×10^{-4}	7.64×10^{-3}	75	6

Table 3
Relevant dimensionless groups.

	LiBr–H ₂ O	LiNO ₃ –NH ₃
<i>Le</i>	88.8	686
<i>Pe_t</i>	164	44.2
δ_1	6.45	1.86
δ_2	10.2	2.95
δ_3	7.62×10^{-3}	2.01×10^{-2}

ically via the algorithm developed for the nonlinear model after imposing $\delta_3 = 0$.

6.3. Analytical solution of the $Le \gg 1$ model

In this case, the series solutions chosen for the normalised mass fraction and temperature in the expanding sheet consist of:

$$\hat{X}(\hat{\xi}, \eta) = C_0 + \sum_{n=1}^{\infty} C_n Q_n(\eta) e^{-\zeta_n^2 \hat{\xi}} \quad (31.a)$$

$$\hat{T}(\hat{\xi}) = D_0 + \sum_{n=1}^{\infty} D_n e^{-\zeta_n^2 \hat{\xi}} \quad (31.b)$$

where $Q_n(\eta) = \cos(\zeta_n \eta)$. The first terms of the series (31) are $C_0 = 1$ and $D_0 = 1$ in order to assure that the normalised mass fraction and temperature tends to one as $\hat{\xi} \rightarrow \infty$. The remaining coefficients are [34]:

$$C_n = \frac{2 \cdot (1 + \delta_2) \cdot \cos(\zeta_n)}{\delta_2 + \cos^2(\zeta_n)} \quad (32.a)$$

$$D_n = \frac{-2(1 + \delta_2)}{\delta_2(1 + \delta_2) + \zeta_n^2} \quad (32.b)$$

The eigenvalue ζ_n should satisfy the transcendental equation,

$$\tan(\zeta_n) = -\frac{\zeta_n}{\delta_2} \quad (33)$$

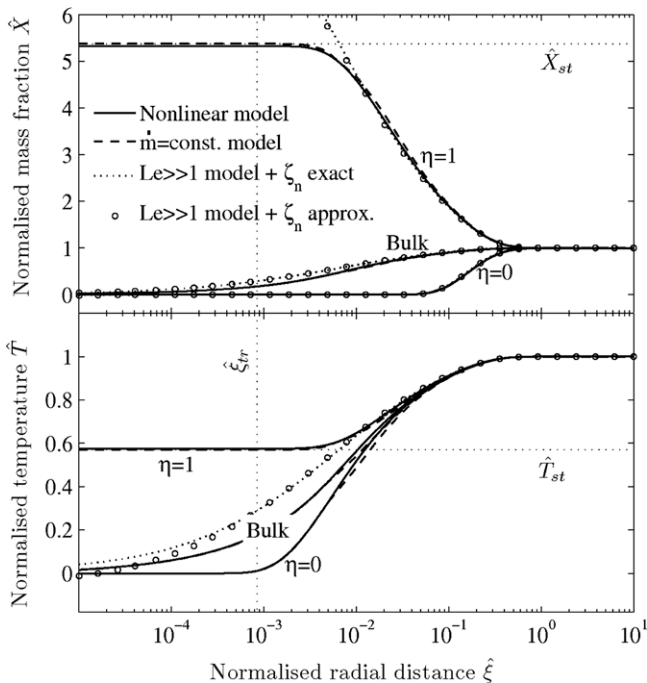


Fig. 3. Radial variation of mass fraction and temperature in the expanding sheet for the pair LiBr–H₂O: local values at two transversal positions, η , and transversally averaged (or bulk) results.

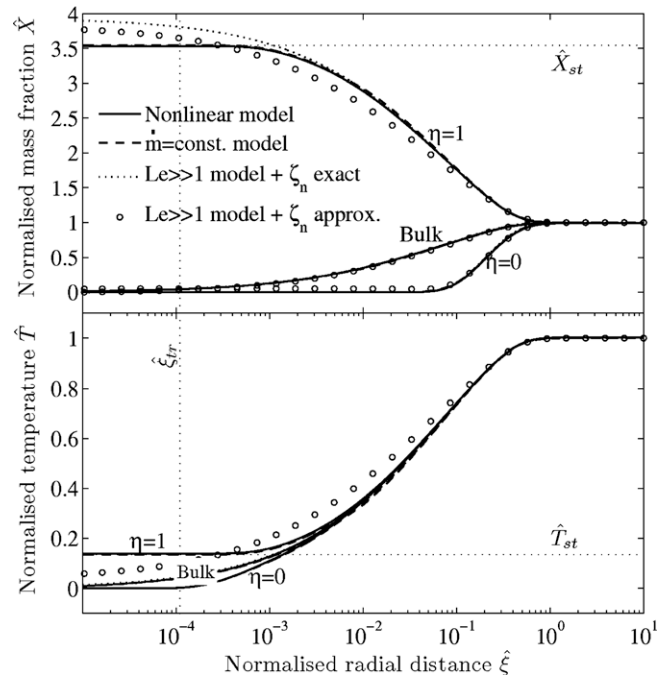


Fig. 4. Radial variation of mass fraction and temperature in the expanding sheet for the pair LiNO₃–NH₃: local values at two transversal positions, η , and transversally averaged (or bulk) results.

which has been obtained by requiring the series (31) to satisfy the boundary condition (26.a). An explicit equation for the estimation of ζ_n is proposed in the present work:

$$\zeta_n \approx \frac{\delta_2 \pi}{8n} \cdot \left(1 - \sqrt{1 + \left(\frac{4n}{\delta_2} \right)^2} \right) + n\pi, \quad n \geq 1 \quad (34)$$

This equation, which is deduced in approximating the tangent function by a rational expression of second order, will be assessed as an alternative of the exact solution of Eq. (33). The accuracy of the eigenvalues estimated using (34) rapidly increases with n and with δ_2 , and is good enough for the calculation of \hat{X} and \hat{T} in practical engineering applications. For example, taking δ_2 values from Table 3, the largest error in accuracy appears in ζ_1 and is less than 0.8% and 4.2% of the exact values that satisfy Eq. (33) in sheets of LiBr–H₂O and LiNO₃–NH₃, respectively.

7. Results and discussion

7.1. Temperature and mass fraction profiles

Figs. 3 and 4 contain the stream-wise computed profiles of normalised mass fraction \hat{X} and temperature \hat{T} for the reference pairs LiBr–H₂O and LiNO₃–NH₃. The plotted results correspond to the four models analysed in this study.

Relevant dimensionless groups used in the simulation can be found in Table 3 based on the operative conditions of Table 2 and the properties of Table 1. Values at the free surface $\eta = 1$, at the centre of the sheet $\eta = 0$ (i.e. the plane of symmetry) and at points in the bulk have been represented in the curves. Bulk values correspond to the normalised transversely averaged mass fraction and temperature:

$$\hat{X}_b(\hat{\xi}) = \frac{X_b - X_0}{X_\infty - X_0} = \int_0^1 \hat{X}(\hat{\xi}, \eta) d\eta; \quad \hat{T}_b(\hat{\xi}) = \int_0^1 \hat{T}(\hat{\xi}, \eta) d\eta \quad (35)$$

Table 4
Main results.

	LiBr–H ₂ O	LiNO ₃ –NH ₃
$\hat{\xi}_{tr}$	8.49×10^{-4}	1.10×10^{-4}
\hat{X}_{st}	5.38	3.55
\hat{T}_{st}	0.571	0.135
Sh_{∞}	1.15	2.25
\overline{Sh}_{∞}	3.19	3.34
$\max(\frac{\dot{m}_w}{\dot{m}_0})$	7.68×10^{-3}	2.05×10^{-2}

The normalised bulk mass fraction is equivalent to the “Approach to Equilibrium Factor F ” [41] when specialised to the case of adiabatic absorption [42], and can be viewed as an efficiency of the absorption process.

Three main regions of flow behaviour are clearly distinguished in the results of the complete nonlinear model: a boundary layer, a transition and a fully developed region.

7.1.1. Boundary layer region

In this initial portion of the sheet, the absorbate mass and the heat transported into the sheet affect only a thin layer close to the free surface. The remaining volume of the sheet is still at the initial temperature and mass fraction conditions. As Figs. 3 and 4 show, this region ranges from the initial position $\hat{\xi} = 0$, to approximately the normalised transition radius $\hat{\xi}_{tr}$ (see Eq. (30)), which has been calculated with $c_k = 0.01$ and included in Table 4. Observe that the boundary layer region is longer for the LiBr–H₂O solution than it is for the LiNO₃–NH₃ solution because the thermal boundary layer reaches the sheet symmetry plane earlier in the ammonia solution (on account of its larger Lewis number).

Normalised absorbent mass fraction \hat{X} and solution temperature \hat{T} stabilise at the free surface of the boundary layer region according to the results of the complete nonlinear model. These local stable values are well predicted by \hat{X}_{st} and \hat{T}_{st} in the boundary

layer approximation theory. The fact that \hat{X} and \hat{T} become stable at the free surface is due to the counteracting effects of mass absorption (which tends to increase solution temperature) and species equilibrium at the surface (which tends to decrease the solution temperature whenever the absorbate mass fraction increases). It should be noticed, however, that the parabolic set of equations (3) and (4), and subsequent models, cease to be valid in a previous region, very close to r_0 , because diffusion along the radial coordinate is not negligible compared to transversal diffusion when $\hat{\xi} \rightarrow 0$. Nevertheless, the contribution of this early region to the total amount of heat and mass transferred into the sheet is negligible since its exposed surface to the vapour is extremely small. This latter fact also explains why the solution is weakly affected by the selection of the initial conditions at the sheet free surface ($\eta = 1$) performed in Eqs. (5) and (6).

The transversal profiles of normalised mass fraction and temperature are depicted in Figs. 5 and 6. The predicted results from the boundary layer model and from the numerical simulation of the entire sheet match almost perfectly inside the boundary layer region, bearing out the correctness of this approximation.

In the boundary layer region, as well as in the rest of the sheet, a numerical solution using the $\dot{m} = const.$ model gives results that are practically indistinguishable from the solution of the complete nonlinear model because common subcooling in adiabatic absorption, of the order of magnitude of 10 °C, is conduent to very small δ_3 (see Table 3). By definition, the approximate model for $Le \gg 1$ cannot provide thermal gradients in the transversal direction and hence fails in predicting the normalised mass fraction at the free surface of the sheet. For clarity, curves of this model have not been included in Figs. 5 and 6 for $\hat{\xi} < \hat{\xi}_{tr}$. Notice that a decrease in Le increases the thermal gradient and reduces the transversal mass fraction gradient in the boundary layer region, since \hat{T}_{st} decreases while \hat{X}_{st} diminishes.

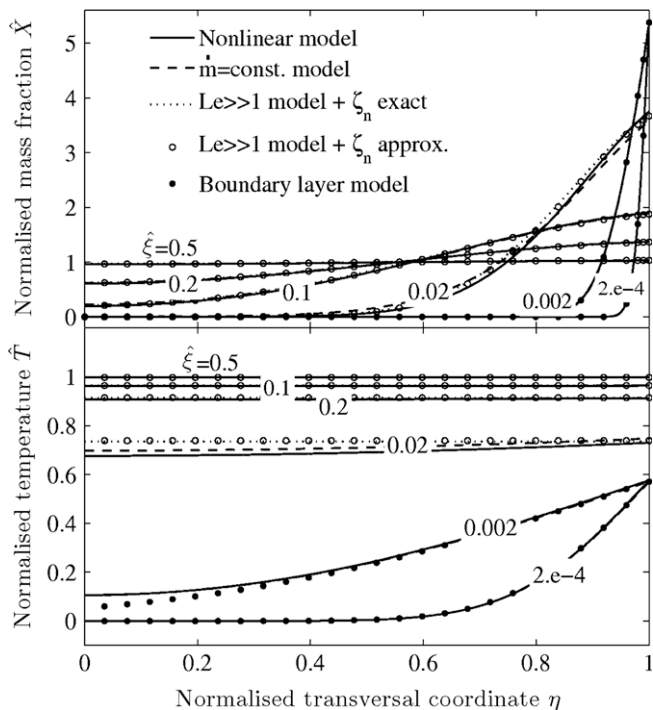


Fig. 5. Transversal profiles of mass fraction and temperature in the expanding sheet for the pair LiBr–H₂O at various normalised radial distances $\hat{\xi}$.

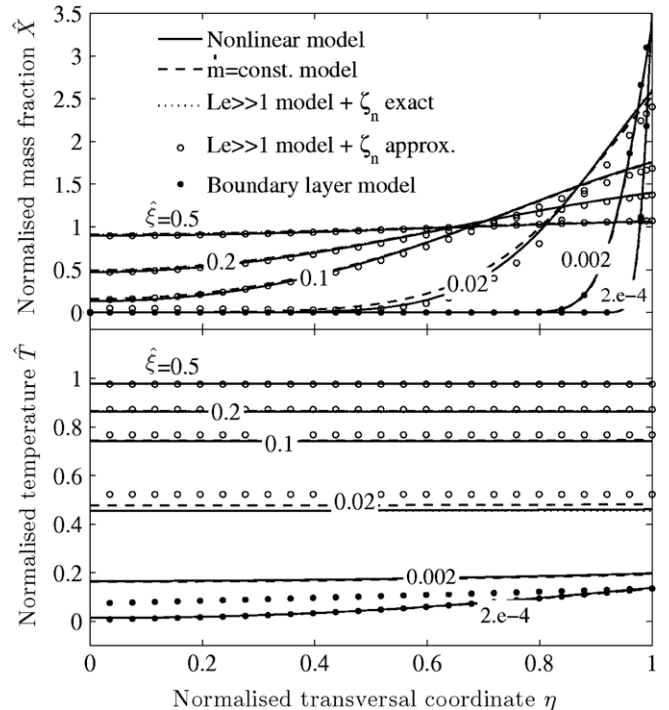


Fig. 6. Transversal profiles of mass fraction and temperature in the expanding sheet for the pair LiNO₃–NH₃ at various normalised radial distances $\hat{\xi}$.

7.1.2. Transition region

A transition region separates the boundary layer behaviour from the final fully developed heat and mass transfer region in the expanding sheet. The transition starts when the temperature boundary layers reach the symmetry plane of the sheet at $\hat{\xi}_{tr}$. From this moment, a change of morphology in the temperature and mass fraction profiles occurs, causing the loss of stable conditions for \hat{T} and \hat{X} at the free surface of the sheet. Numerical solutions of the nonlinear model as well as the $\dot{m} = const.$ model in Figs. 3–6 lend evidence to this fact. The transition region can be considered nearly completed when absorbate mass fraction at the centre of the sheet starts to increase. To be precise, heat and mass transfer in the expanding sheet are not near fully developed until $\hat{\xi} \approx 0.2$, as will be shown later.

Of course it is clear that notorious discrepancies between the nonlinear model and the boundary layer approximation arise in the transition region. This mismatch is shown here in Fig. 6 for $\eta = 0.002$. Using the $Le \gg 1$ model and the exact calculation of ζ_n (Eq. (33)), acceptable results can be obtained in this region for the normalised mass fraction profiles at the sheet surface. This is especially true for the $LiNO_3-NH_3$ solution. In this working pair, the Lewis number is relatively large so that the transversal gradient in temperature is less pronounced than in $LiBr-H_2O$. In fact the actual transversal temperature profiles in the $LiNO_3-NH_3$ solution are practically horizontal within this region, yielding quite accurate predictions of \hat{T} . In the case of the ammonia solution however, the explicit approximation of ζ_n provided by Eq. (34) (hollow circles in the plot) leads to a reduction in the accuracy of the results as δ_2 for this working pair is lower than it is in the aqueous solution. As the analytical solutions for the $Le \gg 1$ model demonstrates, \hat{X}_b tends to \hat{T}_b when Le increases.

7.1.3. Fully developed flow region

After the merger of mass fraction boundary layers, the flow can be regarded as fully developed, in the sense that heat and mass transfer are commanded by the bulk temperature and mass fraction of the flow and not by the shape evolution of their gradients in the sheet. \hat{X} and \hat{T} tend to unity when $\hat{\xi} \rightarrow \infty$ as described in Appendix A. Transversal profiles given in Figs. 5 and 6 show that, for a sufficiently large streamwise distance, transversal gradients of temperature and absorbent mass fraction diminish and their quantities at the surface and at the symmetry plane of the sheet tend to equality with their bulk values. Henceforth, it is in the fully developed zone where the $Le \gg 1$ model, taking ζ_n either exact or approximate, delivers results in very fine agreement with the nonlinear model.

It should be mentioned that the profiles of normalised mass fraction and temperature, described here for expanding sheets, posses a distinctive shape similar to the case of falling-film absorption described in [33,32,37,43].

7.2. Sheet thickness distribution

Fig. 7 contains the normalised thickness profiles along the streamwise direction for the two solution pairs selected in this investigation. $\hat{\varepsilon}$ increases owing to the continuous incorporation of absorbate vapour into the solution during absorption. Indirect calculation of the normalised thickness $\hat{\varepsilon}$ has also been performed knowing that the sheet thickness is directly proportional to the sheet's mass flow rate:

$$\hat{\varepsilon} = \frac{\dot{m}}{\dot{m}_0} = \frac{1}{1 - \delta_3 \hat{X}_b} \tag{36}$$

where $\dot{m}_0 = \pi \varepsilon_0 r_0 \theta \rho V_0 / 180$ is the mass flow rate of solution at the initial position in the sheet and \hat{X}_b is the normalised bulk mass frac-

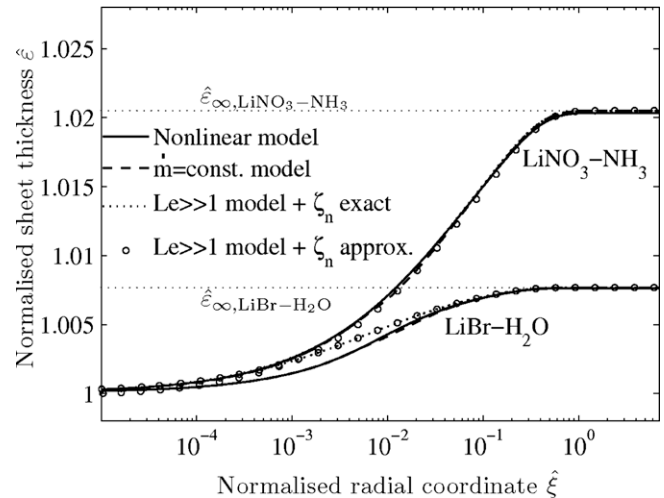


Fig. 7. Radial variation of the normalised sheet thickness for the pairs $LiBr-H_2O$ and $LiNO_3-NH_3$.

tion, Eq. (35). Excellent agreement is encountered in Fig. 7 between $\hat{\varepsilon}$ as calculated directly with the nonlinear model and $\hat{\varepsilon}$ indirectly estimated (through Eq. (36)) using the results of the $\dot{m} = const.$ model. As expected, the $Le \gg 1$ model presents poorer quantitative results in the boundary layer region for the solution with lower Lewis number value ($LiBr-H_2O$). Differences between the results calculated with exact ζ_1 and approximate ζ_1 are not relevant when calculating the sheet thickness. As will be shown later, this is also true for the Sherwood numbers.

Fig. 7 demonstrates that Eq. (36) can be used to obtain accurate estimation of the maximum normalised thickness attainable under complete adiabatic saturation of the sheet when $\hat{\xi} \rightarrow \infty$; that is, when $\hat{X}_b = 1$:

$$\hat{\varepsilon}_\infty = \frac{1}{1 - \delta_3} \tag{37}$$

Under the reference parameters of Table 3, the normalised thickness grows faster with $\hat{\xi}$ and reaches the larger $\hat{\varepsilon}_\infty$ (the largest absorbate absorption per unit of initial solution flow rate) in sheets of $LiNO_3-NH_3$ solution than in sheets of $LiBr-H_2O$.

7.3. Local and mean mass transfer coefficients

In order to characterise the mass transfer coefficients, the local Sherwood number, Sh , and the mean Sherwood number, \bar{Sh} , of the sheet can be calculated using as characteristic lengths the sheet half thickness, $L_c = \varepsilon/2$, and the sheet mean half thickness (sheet volume/free surface area), $\bar{L}_c = \varepsilon_0 / (\xi + 1)$, respectively:

$$Sh = \frac{h_m \cdot L_c}{D} = \frac{1}{X_0 \cdot [\hat{X}(\hat{\xi}, \eta = 1) - \hat{X}_b(\hat{\xi})] \cdot [1 - \delta_3 \hat{X}_b(\hat{\xi})]} \cdot \frac{\partial \hat{X}}{\partial \eta} \Big|_{\eta=1} \tag{38.a}$$

$$\bar{Sh} = \frac{\bar{h}_m \bar{L}_c}{D} = \frac{4Pe_l Le \hat{X}_b}{(\hat{\xi}^2 - 1) \cdot (\hat{\xi} + 1) \cdot X_0 \cdot (1 - \delta_3 \hat{X}_b) \cdot \Delta \hat{X}_{lm}} \tag{38.b}$$

where $h_m = \dot{m}''_v / [\rho(X_b - X_s)]$ is the local heat transfer coefficient [31] at $\hat{\xi}$. $\bar{h}_m = \dot{m}_v / [\rho A_s \Delta X_{lm}]$ is the mean mass transfer coefficient [44], which represents a mean value of h_m throughout the sheet surface $A_s = \pi \theta (r^2 - r_0^2) / 180$ up to a given $\hat{\xi}$. The logarithmic mean absorbate mass fraction difference $\Delta X_{lm} = (\Delta X_0 - \Delta X) / \ln(\Delta X_0 / \Delta X)$ has been included in the \bar{h}_m definition, $\Delta X = X_b - X_s$ being the difference between bulk and surface absorbent mass fractions at $\hat{\xi}$ (ΔX_0 is the same difference evaluated at $\hat{\xi} = 0$) [42]. In Eq. (38.b) $\Delta \hat{X}_{lm}$ is calculated with $\Delta \hat{X} = \hat{X}_s - \hat{X}_b$.

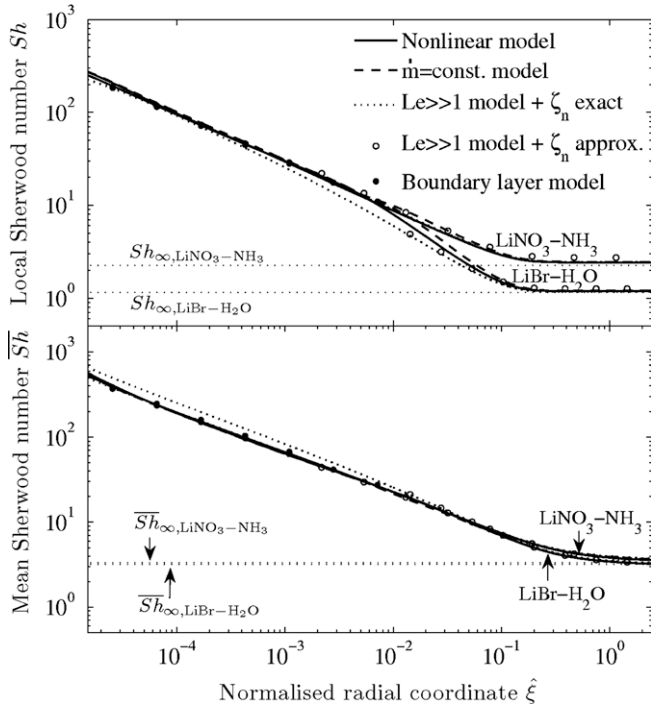


Fig. 8. Radial variation of the local and mean Sherwood numbers in the expanding sheet for the pairs LiBr–H₂O and LiNO₃–NH₃.

Fig. 8 depicts the local and mean Sherwood numbers for the two working pairs under study. Progressive relaxation of the absorbate mass fraction gradient into the sheet monotonically decreases the local Sherwood number from infinite at $\hat{\xi} = 0$ toward a constant asymptotic value Sh_{∞} for $\hat{\xi} \rightarrow \infty$. The mean Sherwood number reproduces this tendency, having always a superior value than its local definition, because very large values of local h_m at initial radial positions significantly increase \bar{h}_m . In general the $\dot{m} = \text{const.}$ model provides almost identical results to the full nonlinear model. Although in qualitative agreement, the $Le \gg 1$ analytical model shows discrepancies in the boundary layer region for the solution with the smaller Le (i.e. LiBr–H₂O). It is also possible to explicitly estimate the Sherwood number in the boundary layer region by substituting Eqs. (28) into (38):

$$Sh_{BL} = \frac{1}{X_0 \cdot (1 - \delta_3 \hat{X}_{st}) \cdot \sqrt{\pi \hat{\xi}}} \approx \frac{1}{X_0 \cdot \sqrt{\pi \hat{\xi}}} \quad (39.a)$$

$$\begin{aligned} \bar{Sh}_{BL} &= \frac{8[Pe_t Le (\hat{\xi}^3 - 1)/3\pi]^{1/2} \hat{X}_{st}}{X_0 \cdot (1 - \delta_3 \hat{X}_{st}) \cdot (\hat{\xi}^2 - 1) \cdot (\hat{\xi} + 1) \cdot \Delta \hat{X}_{lm}} \\ &\approx \frac{8Pe_t Le \hat{\xi}^{1/2} \hat{X}_{st}}{X_0 \cdot \sqrt{\pi} \cdot (\hat{\xi}^2 - 1) \cdot (\hat{\xi} + 1) \cdot \Delta \hat{X}_{lm}} \end{aligned} \quad (39.b)$$

Here, Eq. (28.a) has been used to obtain the normalised bulk mass fraction $\hat{X}_b = 2\hat{X}_{st}(\hat{\xi}/\pi)^{1/2}/(1 - \delta_3 \hat{X}_{st})$ required in $\Delta \hat{X}_{lm}$. Notice that it is obtained a fine accordance between Eqs. (39) and the numerically obtained Sherwood number in the boundary layer region except, notably, for $\hat{\xi}$ very close to zero where numerical integration does not converge to boundary layer self-similar solutions. This excellent agreement confirms the hypothesis that the numerically calculated transport of mass and heat is not substantial in the very early region, prior to the surface stabilisation to \hat{X}_{st} and \hat{T}_{st} . Local Sherwood numbers of the two working pairs exhibit practically coincident Sh_{BL} profiles as both solutions have identical X_0 .

The existence of the asymptotic minimum Sherwood numbers Sh_{∞} and \bar{Sh}_{∞} is due to the full development of the thermal and

mass fraction fields. In view of the local Sherwood profile, it can be said quite rigorously that the coupled heat and mass transfer do not approach fully developed conditions before $\hat{\xi} \approx 0.2$. Including the results of the $Le \gg 1$ model, Eq. (31), into Eq. (38), these fully developed flow Sherwood numbers can be estimated for the limit $\hat{\xi} \rightarrow \infty$:

$$Sh_{\infty} \approx \frac{\zeta_1^2}{X_0 \cdot (1 + \delta_2)} \quad (40.a)$$

$$\bar{Sh}_{\infty} \approx \frac{4}{3} \left(\frac{\delta_2}{Le^{1/2}} + 1 \right) Sh_{\infty} \quad (40.b)$$

where ζ_1 is the first eigenvalue, which can be approximated by Eq. (34) for $n = 1$. According to Fig. 8, Eqs. (40) provide good quantitative approximations in the fully developed region. Eqs. (40) also explain that the Sherwood number for the LiNO₃–NH₃ solution is greater than that for LiBr–H₂O solution because the first working pair has the highest δ_2 (ζ_1 being weakly dependent on δ_2).

7.4. Effect of the aperture angle

Normalised mass fraction, temperature and sheet thickness profiles along $\hat{\xi}$ are independent of the expanding sheet aperture angle θ . This is because its effect is concealed in $\hat{\xi}$ through Pe_t , which is a function of $r_0 = a_0/[2 \sin(\theta/2)]$. This is also true for Sh and it is almost true for \bar{Sh} on account of Eqs. (38). It can be demonstrated that exactly the same dimensionless equations as those deduced in this investigation for expanding sheets arise for non-expanding sheets. This follows provided the next variables are used in non-expanding sheets instead of $\hat{\xi}$, η and $\hat{\varepsilon}$:

$$\hat{\xi}_{NE} = \frac{2y}{Pe_t Le \varepsilon_0}, \quad \eta_{NE} = \frac{2z}{\varepsilon}, \quad \hat{\varepsilon}_{NE} = \frac{\varepsilon}{\varepsilon_0} \quad (41)$$

where y accounts for the streamwise coordinate ($y = 0$ at the initial section of the sheet), ε_0 is the initial thickness of the non-expanding sheet and $Pe_t = V_0 \varepsilon_0 / 2\alpha$ is the Peclet number based on the streamwise velocity of the non-expanding sheet. Note that, in expanding sheets, $y = r - r_0$. Hence, expanding and non-expanding sheets, at a given y , each satisfy the following relation:

$$\hat{\xi} - \hat{\xi}_{NE} = \frac{(Pe_t Le)^2}{3} \cdot \hat{\xi}_{NE}^3 + Pe_t Le \cdot \hat{\xi}_{NE}^2 \quad (42)$$

and thus, $\hat{\xi} - \hat{\xi}_{NE} > 0$. This means that (for similar initial cross-sectional area, equal injection velocity and same working pairs) an expanding sheet configuration of a given (dimensional) length, behaves just as a non-expanding sheet of greater length. Table 5 reports some examples of dimensionless sheet length $\psi = y2/\varepsilon_0$ required for an approach to equilibrium factor of $F = 95\%$ ($\hat{X}_b = 0.95$). Results are calculated with the nonlinear model and fixed a_0 from Table 2. As θ decreases, the sheet length to reach the pre-set 95% saturation increases. The largest ψ takes place always for the ammonia solution because it has the larger product $Pe \cdot Le$. Using the nozzle geometry of Table 2, sheet lengths of 72 or 125 mm are required for LiBr–H₂O or LiNO₃–NH₃ solutions, respectively, in order to reach $F = 95\%$. In general, the larger the angle θ , the greater $\hat{\xi} - \hat{\xi}_{NE}$ and in turn, expanding sheets have a greater performance advantage (higher h_m and A_s) over non-expanding

Table 5
Dimensionless length ψ for $F = 95\%$ and fixed a_0 .

θ [°]	LiBr–H ₂ O	LiNO ₃ –NH ₃
0	1.18×10^5	5.50×10^5
15	2290	3970
75	852	1450
150	631	1073

sheets of similar length. Similar comments for a non-expanding sheet apply to a falling film of initial thickness equal to $e_0/2$ flowing along an adiabatic wall when using a model that approximates the velocity field by a constant profile.

7.5. Effect of the heat of absorption

The heat of absorption has significant influence, through δ_2 (see Eq. (22)), on the heat and mass transfer into the sheet. Fig. 9 shows the sensitivity to δ_2 on the normalised bulk mass fraction \hat{X}_b and on the sheet absorption rate \dot{m}_v/\dot{m}_0 for a solution possessing the same Le and the same dimensionless group $c_1 \Delta T_{sub}/X_0$ than the LiBr–H₂O solution (Table 1). For the sake of clarity, the $Le \gg 1$ model with approximate ζ_1 has not been included in Fig. 9. This model reproduces the same trend as that seen in the \hat{X}_b curves in Figs. 3 and 4. The rate of absorption can be related to \hat{X}_b thanks to the following relation:

$$\frac{\dot{m}_v}{\dot{m}_0} = \hat{\varepsilon} - 1 = \frac{\delta_3 \hat{X}_b}{1 - \delta_3 \hat{X}_b} \approx \delta_3 \hat{X}_b \quad (43)$$

where $\dot{m}_v = \dot{m} - \dot{m}_0$ is the mass flow of vapour absorbed into the sheet from $y = 0$ to a distance ξ . An increase of δ_2 significantly increases \hat{X}_b (Eq. (35)) for a given ξ since X_∞ decreases faster than X_b . For this same reason, \dot{m}_v/\dot{m}_0 reduces with δ_2 so that \bar{h}_m decreases when δ_2 increases, a result supported by Eqs. (39.b) and (40.b). These comments are in agreement with Eq. (43), for which an increase of δ_2 decreases δ_3 to such an extent that both the rate of absorption and the sheet thickness decreases.

The curves for $\delta_2 = 10.2$ in Fig. 9 correspond to the reference case of a LiBr–H₂O working pair. However, the curves associated to $\delta_2 = 2.95$ have a resulting $\delta_3 = 0.0216$ and, consequently, do not exactly match the results for the LiNO₃–NH₃ solution ($\delta_3 = 0.0201$ according to Table 3) depicted in diamond-shaped points in Fig. 9.

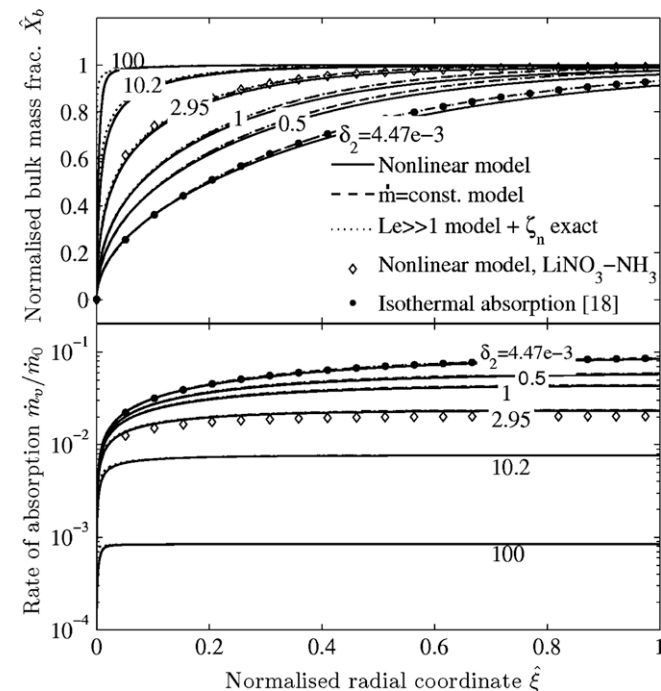


Fig. 9. Effect of the normalised heat of absorption δ_2 on the bulk sheet mass fraction and on the rate of absorption for a solution with the same Le and $c_1 \Delta T_{sub}/X_0$ as the reference case of LiBr–H₂O. Results for the isothermal absorption and for the working pair LiNO₃–NH₃ are also included.

With the aim to evaluate the models in close-to-isothermal conditions, Fig. 9 also depicts the results for $\delta_2 = 4.47 \times 10^{-3}$, corresponding to the absorption of CO₂ into an expanding water sheet. This particular value has been calculated using the equilibrium constant (deduced from Henry’s law [45]) and the heat of absorption of CO₂ into water at 25 °C and at 1 atm [46]. In this special case, the heat of absorption is very small and the increase of temperature in the solution is essentially negligible. This explains why the results for $\delta_2 = 4.47 \times 10^{-3}$ under the approximate models of $\dot{m} = const.$ and $Le \gg 1$ agree perfectly with the isothermal absorption model presented by Tamir and Rachmiev [18].

It is relevant to notice that both the $\dot{m} = const.$ model, the $Le \gg 1$ model and the Tamir and Rachmiev [18] model, are constructed under the hypothesis of the conservation of the flow rate in the sheet. This leads to a slight overprediction of \hat{X}_b as compared to the nonlinear model at medium or large values of ξ . This artificial overprediction of \hat{X}_b occurs because these models provide a smaller mass in which to dissolve the absorbate than is provided in the nonlinear model. For analogous reasons, \hat{T}_b will be also overpredicted in the $\dot{m} = const.$ and in the $Le \gg 1$ models. Nevertheless, the overpredictions in \hat{X}_b and \hat{T}_b get reduced when δ_2 increases toward values that are more commonly encountered in absorption refrigeration. This can be seen in Fig. 9 together with the inaccuracy in \hat{X}_b that appears in the $Le \gg 1$ model at very small ξ and large δ_2 , as this model is not able to resolve large transversal gradients of temperature within the boundary layer region.

7.6. Effect of initial subcooling

The normalised subcooling δ_3 , Eq. (21), is the only parameter of the dimensionless equations that retains the effect of the solution’s initial subcooling ΔT_{sub} . δ_3 has a weak effect on \hat{X} and \hat{T} since the normalisation of these variables partially hides the decrement in X and T caused by an increase of subcooling. Thus, Sh and \bar{Sh} are also weakly affected by δ_3 . Mathematically this is clear as δ_3 is

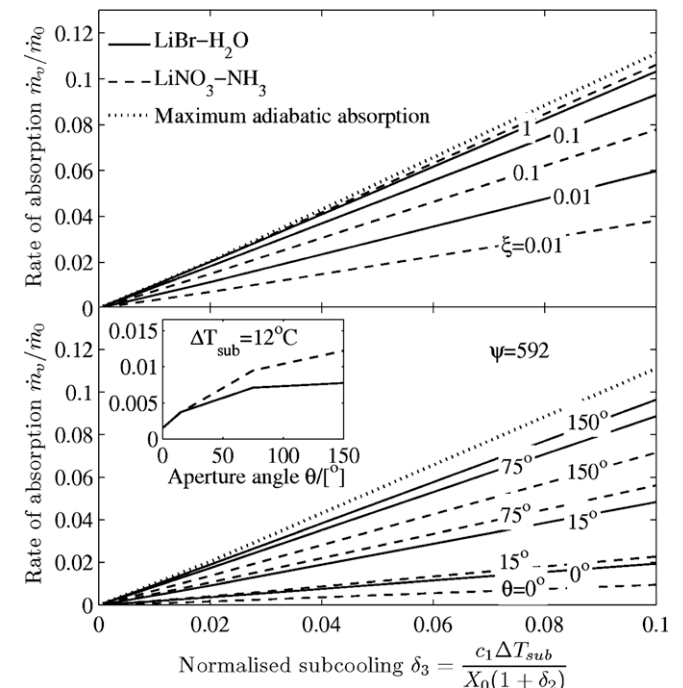


Fig. 10. Effect of subcooling on the rate of absorption into expanding sheets of different normalised radial lengths ξ and aperture angles θ , for the pairs LiBr–H₂O and LiNO₃–NH₃.

absent from the \hat{X} and \hat{T} equations for the $\dot{m} = \text{const.}$ model and from the Eqs. (38). However, δ_3 does possess a strong influence on derived variables such as $\hat{\epsilon}$ and \dot{m}_v/\dot{m}_0 .

Fig. 10 depicts the rate of absorption calculated with the nonlinear model as a function of δ_3 for selected values of $\hat{\xi}$. Results corresponding to different aperture angles θ are also included in Fig. 10 for the initial cross-section parameters of the reference case, a_0 and ϵ_0 , and for a sheet length $y = 0.1$ m ($\psi \approx 592$). \hat{X}_b is constant in each curve of Fig. 10 and the absorption rate increases linearly with the initial subcooling. This fact fully agrees with the approximation provided by the right hand side of Eq. (43). The greater the $\hat{\xi}$ or θ selected for the curve, the higher the sensitivity of the absorption rate on the initial subcooling. Fig. 10 also contains the maximum rate of absorption for a pre-set subcooling, which is reached when $\hat{\xi} \rightarrow \infty$ and $\hat{X}_b \rightarrow 1$ in, for example, infinitely long or extremely thin sheets. According to Eq. (43), the maximum rate of absorption that cannot be surpassed under adiabatic absorption is given by:

$$\max\left(\frac{\dot{m}_v}{\dot{m}_0}\right) = \frac{\delta_3}{1 - \delta_3} \approx \frac{c_1}{X_0(1 + \delta_2)} \Delta T_{sub} \quad (44)$$

Eqs. (43) and (44) do not depend on the flow morphology and, consequently, also apply to other adiabatic absorption configurations using sprays, films and bubbles. Under the reference conditions of Table 1, Eq. (44) leads to $6.85 \times 10^{-4} \Delta T_{sub}$ for LiBr–H₂O solutions and to $1.49 \times 10^{-3} \Delta T_{sub}$ for LiNO₃–NH₃. Therefore, taking the same ΔT_{sub} and a given $\hat{\xi}$ or θ , the ammonia solution has a superior rate of absorption than the aqueous solution if the properties of Table 1 are taken for the comparison. This is also illustrated by the sub-plot in Fig. 10 calculated for 12 °C of subcooling. When substituting for the subcooling of the LiBr–H₂O and LiNO₃–NH₃ solutions (11.1 and 13.5 °C, respectively) the ammonia solution may potentially absorb up to 2.18 times the maximum vapour absorbed by the aqueous solution.

8. Summary and conclusions

In this study, the nonlinear system of equations resulting from modelling the coupled heat and mass transfer during non-isothermal absorption of vapour into laminar expanding liquid sheets has been numerically integrated for two relevant examples of working pairs in absorption refrigeration: LiBr–H₂O and LiNO₃–NH₃. Simplification of this nonlinear set of equations has been conducted by linearising them under the hypothesis of slowly increasing mass flow rate ($\dot{m} \approx \text{const.}$), yielding results that compare well to the nonlinear model over the whole of the expanding sheet. In this regard, the linear model has shown the equivalence between finite dilution effects and the introduction of an equivalent specific heat of absorption L_{abs}^* . Further simplification of the linear equations for the frequent case of large Lewis number ($Le \gg 1$) has been accomplished. The exceptionally simple analytical solution for the $Le \gg 1$ model has been facilitated by an explicit evaluation of the solution eigenvalues that has been proposed in this work. In the transition and in the fully developed region, the $Le \gg 1$ model with exact eigenvalues generates results of satisfactory quality for practical engineering applications, especially for LiNO₃–NH₃ solutions. When approximate eigenvalues are used, the $Le \gg 1$ model is more suitable for LiBr–H₂O solutions. In general, the $Le \gg 1$ model fails in describing the initial region of the sheet, but this is not the case for the boundary layer model adapted to this initial zone.

An analogy of the equations for expanding sheets and for non-expanding sheets, or for falling films over adiabatic walls, has been used in this study to analytically show that expanding sheets always possess better performance than non-expanding sheets. It is also shown that models relying on the mass flow rate conservation assumption slightly overpredict the absorbed mass for working pairs with small normalised heat of absorption δ_2 . Additionally, the local and mean Sherwood numbers have been characterised

and their closed-form analytical expressions determined for the boundary layer and fully developed regions. In particular, it is shown that the mean Sherwood number in expanding sheets is $4/3 \cdot (\delta_2 Le^{-1/2} + 1)$ times the local Sherwood number in the fully developed region. Both dimensionless groups only depend on the initial absorbent mass fraction and the normalised heat of absorption. For the same initial subcooling, and under the conditions of adiabatic absorption selected in this research, the maximum rate of absorption for LiNO₃–NH₃ solutions is larger than for LiBr–H₂O. All these parametric expressions may be applied to the design of adiabatic absorbers, and other processes such as desorption and direct condensation on sheets may benefit from the models and procedures presented in this study.

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Appendix A. Mass fraction and temperature in complete adiabatic saturation

Absorption under adiabatic conditions decreases the absorbent bulk mass fraction X_b and increases the bulk solution temperature T_b toward limiting values. These limiting values are the minimum absorbent mass fraction X_∞ and the maximum temperature T_∞ , which cannot be surpassed by the bulk variables unless, contradicting the adiabatic condition, the solution is cooled during the absorption process. It is possible to estimate X_∞ and T_∞ by means of the following global mass and energy balances performed for an ideal adiabatic absorber in which the solution reaches complete saturation:

$$\dot{m}_0 + \dot{m}_{v\infty} = \dot{m}_\infty \quad (A.1)$$

$$\dot{m}_0 h_0 + \dot{m}_{v\infty} h_v = \dot{m}_\infty h_\infty \quad (A.2)$$

where \dot{m}_0 , \dot{m}_∞ are the liquid solution mass flow rate at the inlet and outlet of the ideal adiabatic absorber (respectively) and $\dot{m}_{v\infty}$ is the mass flow rate of the absorbed vapour. In Eq. (A.2) h_v , h_0 and h_∞ stand for the enthalpies of the absorbent vapour, the solution at the chamber inlet, and the solution at the outlet, respectively. Note that the specific heat of absorption can be approximated by $L_{abs} = h_v - h_0$ and that equilibrium (i.e. $X_\infty = c_1 T_\infty + c_2$) as well as homogeneity take place at the outlet. Owing to the species mass fraction homogeneity at the chamber inlet and outlet, the mass flow rates are intrinsically related to the absorbent mass fraction through $\dot{m}_0/\dot{m}_\infty = X_\infty/X_0$. From Eqs. (A.1) and (A.2), it is straightforward to deduce next the approximate expressions for the absorbent mass fraction and solution temperature reached under complete saturation in adiabatic absorption:

$$X_\infty = \frac{X_0 \cdot (\delta_1 + X_{eq}(T_0))}{\delta_1 + X_0} \quad (A.3)$$

$$T_\infty = \frac{X_\infty - c_2}{c_1} \quad (A.4)$$

where $X_{eq}(T_0)$ is the equilibrium absorbent mass fraction, Eq. (10), at the solution inlet temperature T_0 , and where δ_1 is the dimensionless heat of absorption described in Eq. (19). Any point in a solution sheet of infinite length would theoretically reach X_∞ and T_∞ because in this configuration the exposure time of the solution to

the vapour is limitless and diffusion eliminates transversal gradients. Then, $\hat{X} \rightarrow 1$ and $\hat{T} \rightarrow 1$ if $\hat{\xi} \rightarrow \infty$. According to Eqs. (A.3) and (A.4), and for the properties presented in Table 1, the maximum increments of absorbate bulk mass fraction, i.e. $X_0 - X_\infty$, and bulk temperature, $T_\infty - T_0$, are, respectively, restricted to 4.82×10^{-3} and 10.1°C for LiBr–H₂O solutions, and to 1.27×10^{-2} and 10.08°C for LiNO₃–NH₃ solutions.

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